



# SCHEME & SYLLABUS OF UNDERGRADUATE DEGREE COURSE

# **Electronic Instrumentation & Control Engineering**

**VI Semester** 



Effective for the students admitted in year 2021-22 and onwards.





# B. Tech. Electronic Instrumentation & Control 3<sup>rd</sup> Year – VI Semester

THEORY											
	<b>G</b> (		Course	-	Cor hrs/	ntact week		Ma	rks		Cr
S.No.	Category	Code	Title	L	Т	Р	Exam Hrs.	IA	ETE	Total	
1		6EI4-01	Neural Network and Fuzzy Logic Control	3	0	0	3	30	70	100	3
2		6EI4-02	Process Instrumentation	3	0	0	3	30	70	100	3
3	DC	6EI4-03	Analytical Instrumentation	3	0	0	3	30	70	100	3
4		6EI4-04	Power Electronics	3	0	0	3	30	70	100	3
5		6EI4-05	Embedded Systems	2	0	0	2	30	70	100	2
6	DE	Department	Elective: Any One	2	0	0	2	30	70	100	2
		6EI5-11	Virtual Instrumentation								
		6EI5-12	Digital Image Processing								
		6EI5-13	Robotics								
			Sub-Total	16	0	0		180	420	600	16
			PRACTICAL &	& SES	SIO	NAL					
7		6EI4-20	Control System Simulation Lab	0	0	3	3	60	40	100	1.5
8	DC	6EI4-21	Power Electronics Lab	0	0	3	3	60	40	100	1.5
9		6EI4-22	Analytical Instrumentation Lab	0	0	2	2	60	40	100	1
10	UI	6EI7-50	Mini Project	0	0	4	3	60	40	100	2
11	CCA	6EI8-00	Co-Curricular Activities	0	0	4	-	60	40	100	2
			Sub- Total	0	0	16	-	300	200	500	8
		TOTA	L OF VI SEMESTER	16	0	16	-	480	620	1100	24

L: Lecture, T: Tutorial, P: Practical, Cr: Credits ETE: End Term Exam, IA: Internal Assessment





3<sup>rd</sup> Year- VI Semester: B.Tech. (Electronic Instrumentation & Control Engineering)

**6EI4-01: Neural Network and Fuzzy Logic Control** 

Credits: 03 3L:0T:0P Max. Marks: 100 (IA:30, ETE:70) End Term Exam: 3 Hours

Course Objectives: To impart knowledge of artificial neural network and fuzzy logic systems

#### Course Outcomes: Upon successful completion of the course, students will be able to

**CO-1:** Learn concepts, architecture and working of artificial neural networks

CO-2: Understand supervised and unsupervised learning algorithms

CO-3: Understand Fuzzy set theory and operations, Fuzzy Relations and Fuzzy inference system

CO-4: Design Fuzzy logic controller for industrial applications.

Se.	Contents	Hours
No.		
1.	INTRODUCTION: Objective, Scope and Outcome of the course	1
2.	INTRODUCTION TO ARTIFICIAL NEURAL NETWORKS: Artificial neural	6
	network and their biological motivation, Terminology, Introduction to ANN	
	Architecture, Models of neuron, Topology, Characteristics of artificial neural networks,	
	Types of activation functions.	
3.	LEARNING METHODS: Error correction learning, Hebbian learning, Perceptron, XOR	6
	Problem, Perceptron learning rule, Convergence theorem, Adaline.	
4.	SUPERVISED AND UNSUPERVISED LEARNING: Multilayer Perceptron, Back	7
	propagation learning algorithm, Momentum factor, Radial basis function network,	
	Recurrent neural networks, Hopfield neural network, Competitive learning neural	
	networks, Kohonen self organizing feature map, Counter propagation network.	
5.	FUNDAMENTALS OF FUZZY LOGIC: Introduction to classical sets - Properties,	8
	operations and relations; Fuzzy sets, Uncertainty, Operations, properties, cardinalities,	
	membership functions. Fuzzy relations: Fuzzy cartesian product, Composition-Max min	
	and Max-product composition, Tolerance and Equivalence relations.	
6.	FUZZY INFERENCE SYSTEMS: Fuzzification, Membership value assignment,	8
	Defuzzification to crisp sets, Defuzzification methods, Natural language, Linguistic	
	hedges, Fuzzy rule base system, Graphical techniques of inference.	
7.	FUZZY CONTROL SYSTEM: Basic architecture of Fuzzy logic controller, Industrial	4
	applications- Aircraft landing control, Fuzzy Engineering process control.	
	Total	40

- 1. Timothy J. Ross, Fuzzy Logic with Engineering Applications, John Wiley and sons, 2010.
- 2. Neural Networks, Fuzzy logic, Genetic algorithms: synthesis and applications by Rajasekharan and Rai PHI Publication.
- 3. Introduction to Neural Networks using MATLAB 6.0 S.N.Sivanandam, S.Sumathi, S.N.Deepa, TMH, 2006
- 4. S. Haykin, "Neural Networks, A Comprehensive Foundation", Pearson Education Inc., 2008.





3<sup>rd</sup> Year- VI Semester: B.Tech. (Electronic Instrumentation & Control Engineering)

**6EI4-02: Process Instrumentation** 

Credits: 03 3L:0T:0P Max. Marks: 100 (IA:30, ETE:70) End Term Exam: 3 Hours

**Course Objectives:** To gain knowledge about control of Heat Exchanger, Boiler, Distillation column control, Dryer, Evaporator, Continuous and batch reactor.

# Course Outcomes: Upon successful completion of the course, students will be able to

**CO-1:** Understand the working of Heat Exchanger, Boiler and its control

**CO-2:** Learn design procedures for control of Distillation columns

**CO-3:** Learn the principles and design of controller for Dryers, Reactors

CO-4: Identify various control schemes for Pumps and Compressor

Se.	Contents	Hours
No.		
1.	<b>INTRODUCTION:</b> Objective, Scope and Outcome of the course	1
2.	<b>HEAT EXCHANGER:</b> Operation of heat exchanger, Controlled and manipulated variables in heat exchanger control problem, Degrees of freedom analysis, Instrumentation for feedback, Feed-forward, Feedback-Feed forward control, Cascade control strategies for heat exchanger, PID Tuning methods for heat exchangers, Scaling, Types of scaling, Examples of scaling	6
3.	<b>BOILER CONTROLS:</b> Operation of boiler, Manipulated and controlled variables in boiler control, Safety interlocks and burner management system, Instrumentation for boiler pressure controls, Air to fuel ratio controls, Boiler drum level controls, Steam temperature control, Optimization of boiler efficiency, Boiler blow down, Furnace draft, Ratio control, Selective control, Split range control, Adaptive control, PID tuning methods for boilers.	6
4.	<b>DISTILLATION CONTROLS:</b> Operation of distillation column, Manipulated and controlled variables in distillation column control, Instrumentation for flow control of distillate, Top and bottom composition control, Reflux ratio control, Pressure control schemes, Degree of freedom analysis, Different methods to control distillation with case study.	9
5.	<b>DRYER CONTROLS AND EVAPORATOR:</b> Types and operation of dryers, Controlled and manipulated variables in dryer control problem, Instrumentation for feedback and feed-forward control of various types of dryers, Types and operation of evaporators, Controlled and manipulated variables in evaporator control problem, Instrumentation for feedback, Feed-forward and cascade control strategies for evaporators.	7
6.	<b>CHEMICAL REACTOR CONTROLS:</b> Types of reactions and reactors, Factors governing the conduct of reaction, Stability of reactors, Time constant, Effects of lag, Flow control, Temperature control, pH control, End point detection of continuous and batch reactors, Sequential & logic control in batch process, Batch production management.	6
7.	<b>PUMPS, COMPRESSORS CONTROLS:</b> Pumps: Types, Basic controls, Multi-pump system controls. Compressors: Types, Basic controls, Multi-compressor system controls.	5
	Total	40

- 1. Instrument Engineers' Handbook: Process Control: B.G. Liptak, Chilton.
- 2. Optimization of Industrial Unit Processes Bela G. Liptak
- 3. Boiler Control Systems: David Lindsey, Mc GRAW- HILL
- 4. Process Control Systems- F.G.Shinskey, TMH





3<sup>rd</sup> Year- VI Semester: B.Tech. (Electronic Instrumentation & Control Engineering)

6EI4-03: Analytical Instrumentation

Credits: 03 3L:0T:0P Max. Marks: 100 (IA:30, ETE:70) End Term Exam: 3 Hours

Course Objectives: To impart knowledge of various analytical methods used for solid, liquid and gas sample analysis.

# Course Outcomes: Upon successful completion of the course, students will be able to

CO-1: Learn principles and operation of Spectrophotometry

**CO-2:** Understand spectroscopic methods and their applications

CO-3: Identify various methods for Gas, Liquid and Solid analysis

**CO-4:** Learn functioning of Chromatography and applications.

Se.	Contents	Hours
No.		
1.	<b>INTRODUCTION:</b> Objective, Scope and Outcome of the course	1
2.	ELECTROMAGNETIC RADIATION AND ITS INTERACTION WITH	7
	MATTER: Beer's law, Spectral methods of analysis, Absorption spectroscopy, Radiation	
	sources, Monochromators, Filters, Prisms, Diffraction gratings, Detectors, Choice of	
	solvents, UV-Visible spectrometers, Single-beam and double-beam instruments.	
3.	INFRARED SPECTROPHOTOMETER: IR sources, Cells, Detectors, Sample	7
	preparation, Analysis using Attenuated Total Reflectance (ATR), Atomic absorption	
	spectrometry (AAS), Wavelength choice, Sources, Cells, Detectors, Flame emission	
	spectrometry, Atomic fluorescence spectrometry.	
4.	<b>X-RAY SPECTROSCOPY:</b> X-ray absorption methods, X-ray fluorescence methods, X-	8
	ray diffraction, Radioactive measurement, Units of radioactivity, Application of radio-	
	nuclides in analysis, Radioactivity detectors, Nuclear magnetic Resonance (NMR)	
	spectroscopy, Basic principles, Continuous-wave NMR spectrometer, Pulsed Fourier	
	Transform NMR spectrometer, NMR applications.	
5.	SAMPLING: Sample collection for gas, liquid, and solid analysis, pH measurement,	9
	Basic principles, Ion selective electrodes, Glass and reference electrodes, pH meter and its	
	calibration, Electrical conductivity measurement, Measuring circuit, Water and steam	
	purity measurement using electrical conductivity, Oxygen measurement, Paramagnetic	
	oxygen analyzers, Ceramic electrode for nigh temperature oxygen measurement,	
(	Dissolved oxygen measurement.	0
6.	FLUE GAS ANALYSIS FOR POLLUTION CONTROL: Measurement of CO,	δ
	Carbon DI-Oxide, Dust and smoke measurement, Chromatography, Basic principles of	
	iquid and gas chromatography, Column details, Detectors for chromatography, Therman	
	conductivity detector, Flame forization detector, Flame photometric detector, Electron	
	capture detector, Effect of temperature programming, right pressure liquid	
	Total	40
L	1001	40

- 1. Braun, Robert D., Introduction to Instrumental Analysis, Pharma Book Syndicate, Hyderabad. 2006.
- 2. Jain, R.K., Mechanical and Industrial Measurements, Khanna Publishers, Delhi, 1999.
- 3. Ewing, G.W., Instrumental Methods of Analysis, McGraw Hill, Singapore, 5th Edition, 1992.
- 4. Bela G. Liptak, Instrument Engineers' Handbook, Volume One: Process measurement and analysis, CRC Press, 4th Edition, 2003.
- 5. Considine, D.M. Process/Industrial Instruments and Controls Handbook, McGraw Hill, Singapore, 4th Edition, 1993.
- 6. Sherman, R.E. and Rhodes L.J., Analytical Instrumentation, ISA Press, New York, 1996.





# SYLLABUS 3<sup>rd</sup> Year- VI Semester: B.Tech. (Electronic Instrumentation & Control Engineering) 6EI4-04: Power Electronics

Credits: 03 3L:0T:0P Max. Marks: 100 (IA:30, ETE:70) End Term Exam: 3 Hours

Course Objectives: To impart knowledge of theory and applications of power electronics systems

# Course Outcomes: Upon successful completion of the course, students will be able to

**CO-1:** Understand working of power semiconductor devices.

- **CO-2:** To develop power converters used for the control of DC and AC.
- **CO-3:** To conceptualize and analyze the issues related to recent converter operation

**CO-4:** Identify applications of power electronic devices.

Se.	Contents	Hours
No.		1
1.	<b>INTRODUCTION:</b> Objective, Scope and Outcome of the course	01
2.	POWER SEMICONDUCTOR SWITCHES: Introduction, basic characteristic and	05
	working of Power Diode, Power Transistor, GTO, Power MOSFET and IGBT.	l
	SCR characterstics, Voltage, Current, Load commutation, Driver circuits, Turn-on and	l
	Turn-off characteristics.	L
3.	AC TO DC CONVERTERS: Natural commutation, Single-phase and three-phase bridge	04
	rectifiers, Semi controlled and fully controlled rectifiers, Dual converters.	1
4.	DC TO DC CONVERTERS: Buck, Boost, Buck-Boost converters	06
5.	DC TO AC CONVERTERS: Single-phase VSI, Three-phase VSI, Voltage control,	09
	Pulse-width modulated (PWM) inverters, Single and multiple PWM, Sinusoidal PWM	l
	(SPWM), Modified SPWM, Space vector modulation and hysteresis band current control	l
	PWM techniques. PWM based inverters and resonant converters	L
6.	AC TO AC CONVERTERS: Single-phase AC voltage controllers, Multistage sequence	08
	control, single and three phase cycloconverters, Introduction to Integral cycle control,	l
	Power factor control and Matrix converters.	1
7.	APPLICATIONS OF POWER ELECTRONICS: UPS, SMPS and Reactive power	07
	compensation.	
	Total	40

- 1. Rashid M. H, Power Electronics Circuits, Devices and Applications, Prentice Hall, New Delhi, 4thEdition, 2013.
- 2. Dubey G. K, Doradla S.R, Joshi and Sinha R.M, Thyristorised Power Controllers, New Age International Publishers, New Delhi, 2010.
- 3. John G. Kassakian, Principles of Power electronics, Addison Wesley, 1991.
- 4. P. S. Bimbhra, Power Electronics, Khanna Publishers, 5th Edition, 2012.
- 5. Vedam Subramanyam K, Power Electronics, New Age International Publishers, New Delhi, 2nd Edition, 2012.
- 6. Mohan, Undeland and Robbins, Power Electronics: Converters, Applications and Design, John Wiley and Sons, New York, 1995.
- 7. Joseph Vithyathil, Power Electronics, McGraw Hill, New York, 1995.





3<sup>rd</sup> Year- VI Semester: B.Tech. (Electronic Instrumentation & Control Engineering)

#### **6EI4-05: Embedded Systems**

Credits: 02 2L:0T:0P Max. Marks: 100 (IA:30, ETE:70) End Term Exam: 2 Hours

**Course Objectives:** To familiarize the students with the fundamentals of embedded system architecture, its basic hardware and software elements, software engineering practices that are used during the system development process.

#### Course Outcomes: Upon successful completion of the course, students will be able to

- CO-1: Learn the architecture and functioning of advanced processors
- **CO-2:** Learn the Programming concepts of embedded systems.

**CO-3:** Understand the real time operating systems

Se.	Contents	Hours
No.		
1.	<b>INTRODUCTION:</b> Objective, Scope and Outcome of the course	01
2.	INTRODUCTION TO EMBEDDED SYSTEMS: Embedded system, processor in the	03
	system, Hardware and software components, System-on chip.	
3.	REVIEW OF PROCESSOR AND MEMORY: General-purpose processors, Single-	06
	purpose processors, Application specific processors, CISC and RISC processor	
	architecture, ARM processors, Memory devices, Processor and memory selection for an	
	embedded system, Interfacing processor, Memory and I/O devices, 8/16 bit	
	microcontrollers.	
4.	DEVICES AND BUSES: Review of I/O and timer devices, Parallel communications	06
	using ISA, PCI and other buses, Serial communication using I <sup>2</sup> C, CAN, USB and	
	advanced buses, Interrupt serving mechanism, Device drivers.	
5.	EMBEDDED PROGRAMMING: Review of programming in ALP and in C, Embedded	06
	programming in C++, Memory organization, Compiler and cross compiler.	
6.	REAL TIME OPERATING SYSTEMS: Operating system services, I/O subsystems,	04
	Network operating systems, Embedded system operating systems, Interrupt routines in	
	RTOS environment.	
7.	HARDWARE-SOFTWARE CO-DESIGN: Embedded system design and co-design	04
	issues, Software tools for development of an embedded system	
	Total	30

- 1. Kamal R., "Embedded Systems Architecture, Programming and Design", Tata McGraw-Hill Publishing Company Limited.
- 2. Vahid F. and Givargis T., "Embedded System Design A Unified Hardware/Software Introduction", Wiley India.
- 3. Maxfield C. M., "The Design Warrior's Guide to FPGAs Devices, Tools and Flows", Newnes.
- 4. Berger A. S., "Embedded System Design An Introduction to Processes, Tools and Techniques", CMP Books.
- 5. Labrosse J. J., "Embedded Systems Building Blocks", 2<sup>nd</sup> Ed., CMP Books.
- 6. Barr M., "Programming Embedded Systems in C and C++", O'Reilly.





# SYLLABUS 3<sup>rd</sup> Year- VI Semester: B.Tech. (Electronic Instrumentation & Control Engineering) 6EI5-11: Virtual Instrumentation (Department Elective)

Credits: 02 2L:0T:0P Max. Marks: 100 (IA:30, ETE:70) End Term Exam: 2 Hours

Course Objectives: To impart knowledge of virtual instrumentation and software tools

# Course Outcomes: Upon successful completion of the course, students will be able to

CO-1: Understand the concept of virtual instrumentation

**CO-2:** Learn data flow programming using LABVIEW software

**CO-3:** Learn communication and interfacing protocol for VI models.

**CO-4:** Develop virtual instrument for modeling, monitoring and control of real time processes.

Se.	Contents	Hours
No.		
1.	INTRODUCTION: Objective, Scope and Outcome of the course	01
2.	Introduction to Virtual Instrumentation: Historical perspective, Classification of	05
	different instruments / instrumentation system. Definition and architecture of virtual	
	instrumentation system, salient features and application area of virtual	
	instrumentation.	
3.	Data Flow Programming Techniques: Graphical programming in data flow,	07
	comparison with conventional programming, popular data flow and VI software	
	packages. Building a VI front panel and block diagram, sub VI, for and while loops,	
	case and sequence structure, formula nodes, local and global, string and file I/O, array	
	and clusters, charts and graphs, attributes nodes.	
4.	Data Acquisition Basics: ADC, DAC, D/O, counters and timer, PC hardware	06
	structure, timing, interrupts, DMA, software and hardware installation, Configuring	
	data acquisition hardware using the drives in application software, use of DAQ library	
	functions for different analog and digital input/output operations.	
5.	Common Instrument Interfaces: Current loop, RS 232, RS485, GBIP. Use of	05
	library functions to communicate with different instruments.	
6.	Use of Measurement Analysis Tools: Measurement of Max, Min, Peak-Peak	06
	voltage, Mathematical tools, time period of a signal, power spectrum and logging	
	Fourier transform, Correlation methods, windowing and filtering. Building a web	
	based virtual instrument: Networking basics for office and industry application.	
	Total	30

- 1. Lisa, K. Wells & Jeffery Travis / Lab VIEW For every one Prentice Hall, 19972.
- 2. S. Gupta / P.C Interfacing for data Acquisition & Process Control, 2nd Edition / Instrument Society of America, 1994.
- 3. Gray Johnson / Lab VIEW Graphical Programming 2nd Edition / Tata McGraw Hill, 1997.
- 4. Bitter, Mohiuddin, Nawrocki / Advanced Cal VIEW Programming Techniques.
- 5. NI manual for LABVIEW





# SYLLABUS 3<sup>rd</sup> Year- VI Semester: B.Tech. (Electronic Instrumentation & Control Engineering) 6EI5-12: Digital Image Processing (Department Elective)

Credits: 02 2L:0T:0P Max. Marks: 100 (IA:30, ETE:70) End Term Exam: 2 Hours

Course Objectives: To impart knowledge of digital image processing techniques and applications.

# Course Outcomes: Upon successful completion of the course, students will be able to

**CO-1:** Understand fundamentals of image processing.

CO-2: Learn the concepts of image restoration and compression

**CO-3:** Explore the concepts of image segmentation

Se.	Contents	Hours
No.		
1.	<b>INTRODUCTION:</b> Objective, Scope and Outcome of the course	01
2.	BASICS CONCEPTS OF IMAGE PROCESSING: Digital Image representation,	05
	representation.	
3.	<b>IMAGE TRANSFORMATION &amp; FILTERING:</b> Intensity transform functions, Histogram processing, Spatial filtering, Fourier transforms and its properties, Frequency domain filters, Colour models, Pseudo colouring, Colour transforms, Basics of wavelet transforms.	06
4.	<b>IMAGE RESTORATION:</b> Image degradation and restoration process, Noise models, Noise filters, Degradation function, Inverse filtering, Homomorphism filtering.	06
5.	<b>IMAGE COMPRESSION:</b> Coding redundancy, Inter pixel redundancy, Psycho visual redundancy, Huffman coding, Arithmetic coding, Lossy compression techniques, JPEG compression.	06
6.	<b>IMAGE SEGMENTATION &amp; REPRESENTATION:</b> Point, Line and Edge Detection, Thresholding, Edge and Boundary linking, Hough transforms, Region based segmentation, Boundary representation, Boundary descriptors.	06
	Total	30

- 1. Gonzalez & Woods, Digital Image Processing, Pearson education, 3rd Edition, 2008.
- 2. Jain Anil K., Fundamentals Digital Image Processing, Prentice Hall India, 2010.
- 3. Milan Sonka, Vaclav Hlavav, Roger Boyle, Image Processing, Analysis and Machine Vision, Thomson Learning, 2nd Edition, 2001.
- 4. Pratt W.K, Digital Image Processing, John Wiley & Sons, 3rd Edition, 2007.





# SYLLABUS 3<sup>rd</sup> Year- VI Semester: B.Tech. (Electronic Instrumentation & Control Engineering) 6EI5-13: Robotics (Department Elective)

Credits: 02 2L:0T:0P Max. Marks: 100 (IA:30, ETE:70) End Term Exam: 2 Hours

Course Objectives: To impart knowledge about robotics, its dynamics and applications

#### Course Outcomes: Upon successful completion of the course, students will be able to

CO-1: Learn basic building block of robotics and automation

CO-2: Understand dynamics and control of robotics

**CO-3:** Gain knowledge about programming concepts used in robotics

**CO-4:** Find various application of robotics

Se.	Contents	Hours
No.		
1.	<b>INTRODUCTION:</b> Objective, Scope and Outcome of the course	01
2.	BASICS OF ROBOTICS: Concepts, Definition and origin of robotics, Different types of	06
	robots, Robot classification, Applications, Robot specifications.	
3.	INTRODUCTION TO AUTOMATION: Components and subsystems, Basic building	05
	block of automation, Manipulator arms, Wrists and end-effectors, Transmission elements,	
	Hydraulic, Pneumatic and electric drives, Gears, Sensors, Materials, User interface,	
	Machine vision, Implications for robot design, Controllers.	
4.	KINEMATICS, DYNAMICS AND CONTROL: Object location, Three dimensional	06
	transformation matrices, Inverse transformation, Kinematics and path planning, Jacobian	
	work envelope, Manipulator dynamics, Dynamic stabilization, Position control and force	
	control, Present industrial robot control schemes.	
5.	ROBOT PROGRAMMING: Robot programming languages and systems, Levels of	06
	programming robots, Control of industrial robots using PLCs.	
6.	AUTOMATION AND ROBOTS: Case studies, Multiple robots, Machine interface,	06
	Robots in manufacturing and non-manufacturing applications, Robot cell design,	
	Selection of a robot.	
	Total	30

- 1. Spong, M.W., Hutchinson, H., & Vidyasagar, M., Robot Modeling and Control, John Wiley (Wiley India Ed.), 2006.
- 2. Asfahl C.R, Robots and Manufacturing Automation, John Wiley & Sons, New York, 1992.
- 3. Klafter R.P, Chmiclewski T.A, Negin M, Robotics Engineering: Integrated approach, Prentice Hall, New Jersey, 1994.
- 4. Mikell P, Weiss G.M, Nagel R.N and Odrey N.G, Industrial Robotics, McGraw Hill, New York, 1986.





# SYLLABUS 3<sup>rd</sup> Year- VI Semester: B.Tech. (Electronic Instrumentation & Control Engineering) 6EI4-20: Control System Simulation Lab

Credits: 1.5 0L:0T:3P Max. Marks: 100 (IA:60, ETE:40)

Course Objectives: To impart practical knowledge of simulation of control systems

# Course Outcomes: Upon successful completion of the course, students will be able to

**CO-1:** Analyze the systems transient and frequency response

**CO-2:** Find response of systems for standard inputs

CO-3: Find stability analysis of given systems

**CO-4:** Design controller for the given system

Se. No.	Name of Experiments
1.	Introduction: Objective, scope and outcome of the course.
2.	Introduction to `MATLAB'. Computing control software, defining systems in TF, ZPK form.
3.	Use of for, while loops in MATLAB programming.
4.	<ul><li>(a) Plot step response a given TF and system in state-space. Take different valves of damping ratio and natural undamped frequency and observe the difference.</li><li>(b) Plot ramp and impulse response for the same.</li></ul>
5.	For a given 2nd order system write a program to obtain time response specifications maximum overshoot, peak time, settling time etc.
6.	Write a program to check for the stability of a given closed loop system by (a) Finding close loop poles (b) using Routh's stability criterion.
7.	Sketch the root locus for a given system and determine the system gain. Also simulate the same using MATLAB.
8.	Sketch the Bode plot for a given system and analyses the stability. Also simulate the same using MATLAB and find the values of GM and PM
9.	Design of lead controller to satisfy given specifications using bode plot.
10.	Use MATLAB to plot Nyquist plot for a given system and comment upon stability.
11.	To design a PID controller for the given system to meet desired specifications. Observe the response using MATLAB.





# SYLLABUS 3<sup>rd</sup> Year- VI Semester: B.Tech. (Electronic Instrumentation & Control Engineering) 6EI4-21: Power Electronics Lab

Credits: 1.5 0L:0T:3P Max. Marks: 100 (IA:60, ETE:40)

Course Objectives: To impart practical knowledge of various power electronics devices

# Course Outcomes: Upon successful completion of the course, students will be able to

CO-1: Learn the characteristics and operation of thyristor family

**CO-2:** Design of controllers for various applications.

CO-3: Learn switching behavior and design of converter and inverter circuits

Se. No.	Name of Experiments
1.	Study the characteristics of SCR and observe the terminal configuration, measure the breakdown voltage, latching and holding current. Plot V-I characteristics.
2.	Perform experiment on triggering circuits for SCR. i.e. R triggering, R-C triggering and UJT triggering circuit.
3.	Study and test AC voltage regulators using Triac, anti parallel Thyristors and Triac & Diac.
4.	Study and obtain the waveforms for single-phase bridge converter.
5.	Perform experiment on single phase PWM inverter.
6.	Perform experiment on buck, boost and buck-boost regulators.
7.	Control speed of a dc motor using a chopper and plot armature voltage versus speed characteristic.
8.	Control speed of a single-phase induction motor using single phase AC voltage regulator.
9.	<ul><li>(i) Study single-phase dual converter</li><li>(ii) Study speed control of dc motor using single-phase dual converter</li></ul>
10.	Study single-phase cyclo converter.
11.	Perform experiment on motor control – open loop & closed loop.
12.	Design, observe and perform experiment on various type of pulse generation from DSP/ FPGA platform. Perform experiment for PWM inverters and choppers.





# SYLLABUS 3<sup>rd</sup> Year- VI Semester: B.Tech. (Electronic Instrumentation & Control Engineering) 6EI4-22: Analytical Instrumentation Lab

Credits: 1 0L:0T:2P Max. Marks: 100 (IA:60, ETE:40)

Course Objectives: To impart practical knowledge of analytical instruments and their characteristics

# Course Outcomes: Upon successful completion of the course, students will be able to

**CO-1:** Find analytical parameters of air/gas

CO-2: Find characteristics of different solutions and find their analytical parameters

**CO-3:** Understand characteristics and working principle of Spectrophotometer

**CO-4:** Learn characteristics and working principle of Chromatograph

Se.	Name of Experiments
No.	
1.	To measure pH value of given solution using pH meter.
2.	To determine suspended particular matter using right volume air samples.
3.	Find out concentration of (Na or K) by flame photo meter in the given sample.
4.	To measure transmittance and absorption of a solution using Single beam Spectrophotometer.
5.	To study water analysis kit & measure pH, temperature, conductivity, dissolved O <sub>2</sub> of a given solution.
6.	To measure the conductivity of solution indicator controller.
7.	To study the analysis of flue gases.
8.	To study ion selective electrode.
9.	To study pH monitor and controller.
10.	To study gas/ liquid Chromatograph.